

Embedded Systems Reverse Engineering

// WEEK 03

Embedded System Analysis:
Understanding the RP2350 Architecture
w/ Comprehensive Firmware Analysis

George Mason University

RP2350 // ARM Cortex-M33

RP2350 Boot Sequence

Power-On to main() – 5 Steps

STEP 1 Power On

Cortex-M33 wakes, execution at 0x00000000 (Bootrom)



STEP 2 Bootrom Executes

32KB on-chip ROM – finds IMAGE_DEF at 0x10000000



STEP 3 Boot Stage 2 (boot2)

Configures flash interface, sets up XIP mode



STEP 4 Vector Table & Reset Handler

Reads SP from offset 0x00 -> 0x20082000

Reads Reset Handler from 0x04 -> 0x1000015d



STEP 5 C Runtime Startup (crt0.S)

Copy .data from flash -> RAM

Zero .bss section

Call runtime_init() -> main()

Key Insight

Your main() is the LAST thing to run.

All 5 steps must complete first!

The Bootrom

32KB Factory-Programmed ROM — Where It All Begins

Bootrom Properties

Size	32 KB
Location	0x00000000
Modifiable?	NO — mask ROM
Purpose	Boot the chip

Burned into silicon at factory
Like BIOS in your computer

What It Does

1. Initialize hardware
2. Check boot sources
3. Validate IMAGE_DEF
4. Configure flash
5. Jump to your code

IMAGE_DEF — Magic Markers

Bootrom looks for these to validate firmware

Start Marker	0xFFFFDED3	"I'm a valid Pico binary!"
End Marker	0xAB123579	"End of header block"

Bootrom reads flash at 0x10000000,
finds these markers, then boots.

XIP — Execute In Place

Run Code Directly from Flash — No Copy Needed

Book Analogy

Without XIP

Photocopy every page, read copy

With XIP

Read directly from the book!

Why Use XIP?

Saves RAM

Code stays in flash

Faster Boot

No bulk copy needed

Simpler

Less memory mgmt

XIP Flash Region at 0x10000000

Vector Table

0x10000000

SP at offset 0x00 | Reset Handler at offset 0x04 | Exception handlers...

Your Code

0x100001xx

_reset_handler | main() | other functions

Read-Only Data

0x10001xxx

Strings like "hello, world" | constant values

CPU fetches instructions directly
from flash via XIP cache.

The Vector Table

CPU's Instruction Manual at 0x10000000

Vector Table Layout

Offset	Address	Value	Meaning
0x00	0x10000000	0x20082000	Initial SP
0x04	0x10000004	0x1000015D	Reset Handler
0x08	0x10000008	0x1000011B	NMI Handler
0x0C	0x1000000C	0x1000011D	HardFault Handler

GDB: x/4x 0x10000000

On Power-On

- CPU reads SP from 0x00
- Sets SP = 0x20082000
- Reads Reset from 0x04
- Jumps to 0x1000015C

Default Handlers

NMI, HardFault, SVCall,
PendSV, SysTick all use:

bkpt 0x0000 <- stops debugger

Thumb Mode Addressing

Why Addresses End in Odd Numbers

The LSB Rule

ARM Cortex-M uses the Least Significant Bit (LSB) to indicate instruction mode:

LSB = 1 (odd)

Thumb mode

LSB = 0 (even)

ARM mode

Reset Handler Example

Vector table stores: **0x1000015D**

Actual code address: **0x1000015C**

The +1 means: **"Use Thumb mode"**

GDB Shows

0x1000015D

with Thumb bit

Vector table raw value

Ghidra Shows

0x1000015C

actual address

Real instruction location

Both are correct — just displayed differently!

Linker Script Memory Map

memmap_default.ld – Where Everything Lives

Memory Regions

Flash (XIP)	0x10000000	varies	Your code (read-only)
RAM	0x20000000	512 KB	Main RAM (r/w)
SCRATCH_X	0x20080000	4 KB	Core 0 scratch
SCRATCH_Y	0x20081000	4 KB	Core 0 stack!

Stack Pointer Calculation

```
__StackTop = ORIGIN(SCRATCH_Y)  
+ LENGTH(SCRATCH_Y)
```

```
ORIGIN      0x20081000      + LENGTH      0x1000      (4 KB)  
  
= __StackTop = 0x20082000      <- matches vector table!
```

Reset Handler – 4 Phases

_reset_handler at 0x1000015C

Phase 1: Core Check

0x1000015C – 0x10000168

```
mov r0, #0xD0000000
```

Read CPUID -> Core 0 continues

Phase 2: Data Copy

0x1000016A – 0x10000176

```
ldmia r4!, {r1,r2,r3}
```

Copy .data from flash -> RAM

Phase 3: BSS Clear

0x10000178 – 0x10000184

```
stmia r1!, {r0}    r0 = 0
```

Zero all uninitialized globals

Phase 4: Platform Entry

0x10000186+

```
blx r1    -> main()
```

runtime_init -> main -> exit

Execution Flow

Core Check

CPUID == 0?

->

Data Copy

flash -> RAM

->

BSS Clear

zero globals

->

Platform Entry

-> main()!

Why check cores?

RP2350 has 2 cores.

Only Core 0 runs startup.

Core 1 returns to bootrom and waits.

Data Copy & BSS Clear

Initializing RAM Before main() Can Run

Phase 2: Data Copy

Copy initialized variables flash -> RAM

C code:

```
int counter = 42;
```

Value 42 stored in flash
but variables live in RAM!

Flash

->

RAM

data_cpy_table has entries:

```
src: 0x10001B4C (flash)
dst: 0x20000110 (RAM)
```

Phase 3: BSS Clear

Zero uninitialized global variables

C code:

```
int my_counter;
```

C standard requires
this to start at zero.

```
r1 = BSS start
r2 = BSS end
r0 = 0
```

```
Loop: store 0, advance r1
Until r1 == r2 -> done!
```

Key Assembly Instructions

```
ldmia r4!, {r1,r2,r3}
```

Load source, dest, end from table

```
bl data_cpy
```

Copy word-by-word until done

```
movs r0, #0
```

Load zero into r0

```
stmia r1!, {r0}
```

Store zero, advance pointer

Platform Entry -> main()

The Final Step – 3 Function Calls at 0x10000186

platform_entry Assembly

0x10000186 `ldr r1, [DAT]` -> load runtime_init addr

0x10000188 `blx r1` -> call runtime_init()

0x1000018C `blx r1` -> call main()

0x10000190 `blx r1` -> call exit()

Call Sequence

runtime_init()

SDK setup

->

main()

YOUR CODE

->

exit()

cleanup

runtime_init()

Initializes SDK systems:

- Clock configuration
- GPIO setup
- C++ constructor calls
- Peripheral initialization

After main() Returns

exit() handles cleanup.

Then:

bkpt 0x0000 <- infinite halt

Should never be reached!

Secure Boot & Attack Vectors

Why Boot Sequence Knowledge Matters for Security

Attack Scenarios

Firmware Replacement

Replace flash with malicious code

Vector Table Hijack

Modify reset handler address

Debug Port Attack

SWD/JTAG to dump or inject code

Startup Code Modification

Change crt0 data copy / BSS init

Physical access = game over

Defense Strategies

1. Secure Boot

2. Debug Port Lock

3. Flash Read Protect

4. MPU Configuration

5. Integrity Checks

Defense in depth!

Secure Boot Chain

Bootrom

immutable

->

Verify Sig

IMAGE_DEF

->

Verify App

signature

->

Boot!

or refuse

Each stage cryptographically verifies the next before handing off control.

Bootrom = trust anchor (can't be changed)